

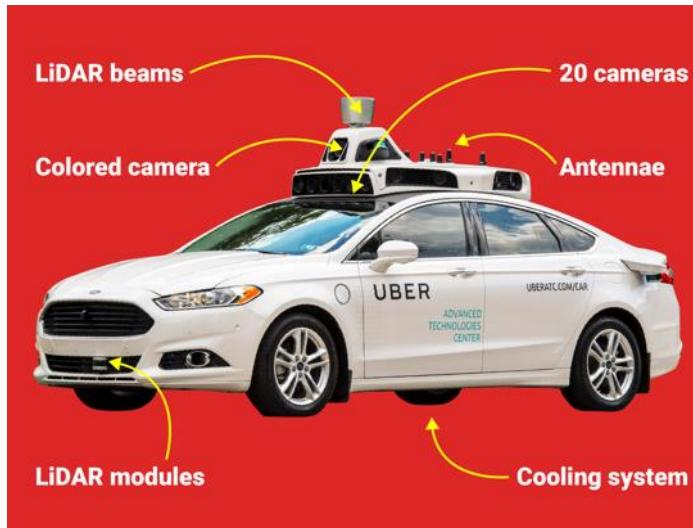
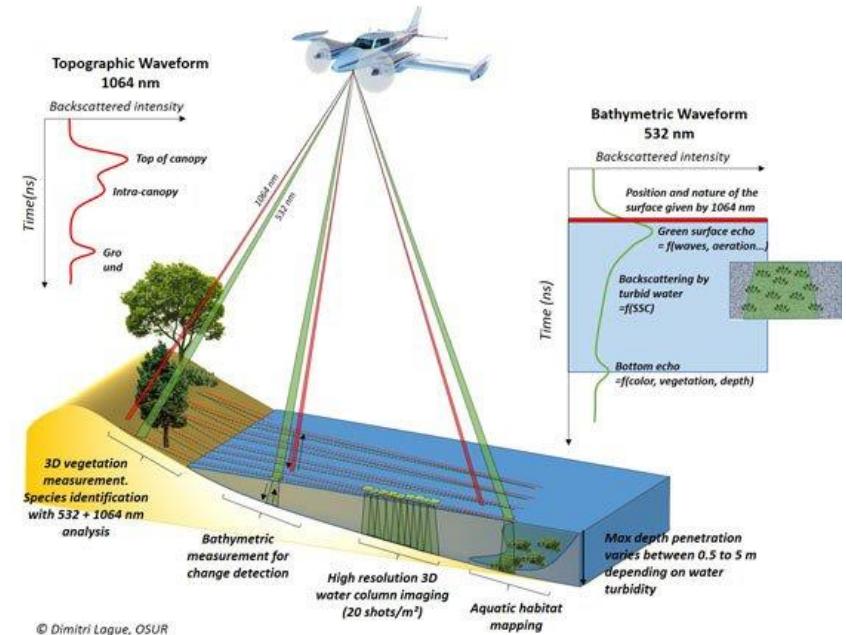
Bruk av LiDAR for modellering av geometri og hydraulikk

Knut Alfredsen

Institutt for bygg og miljøteknikk

NTNU

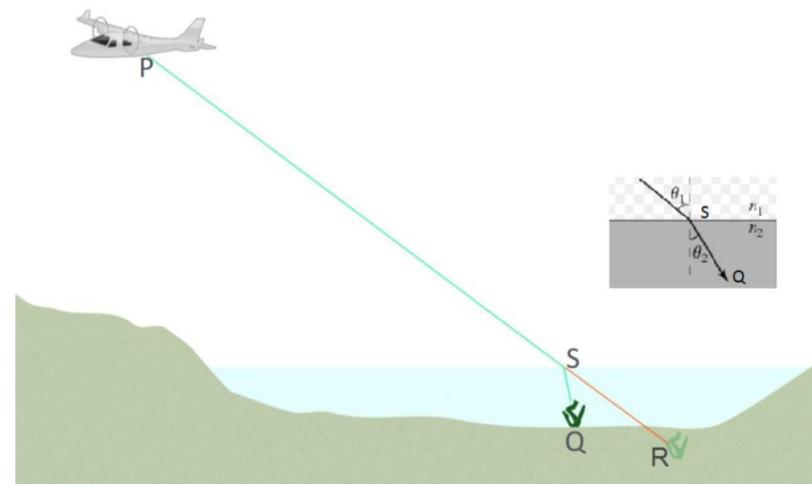
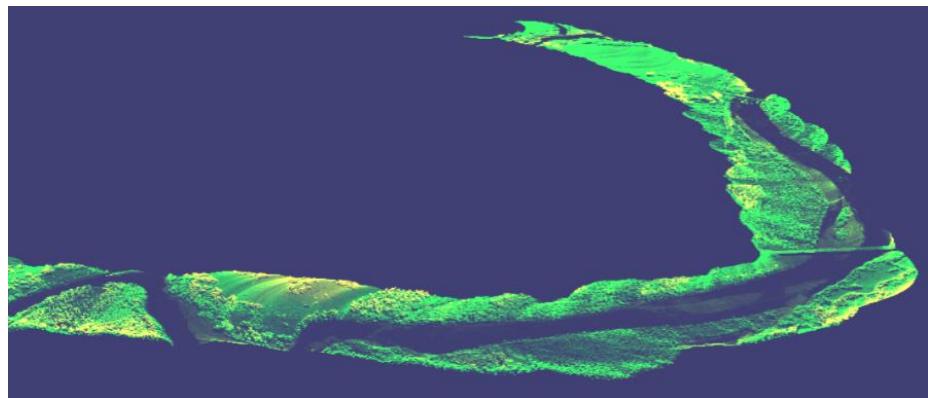
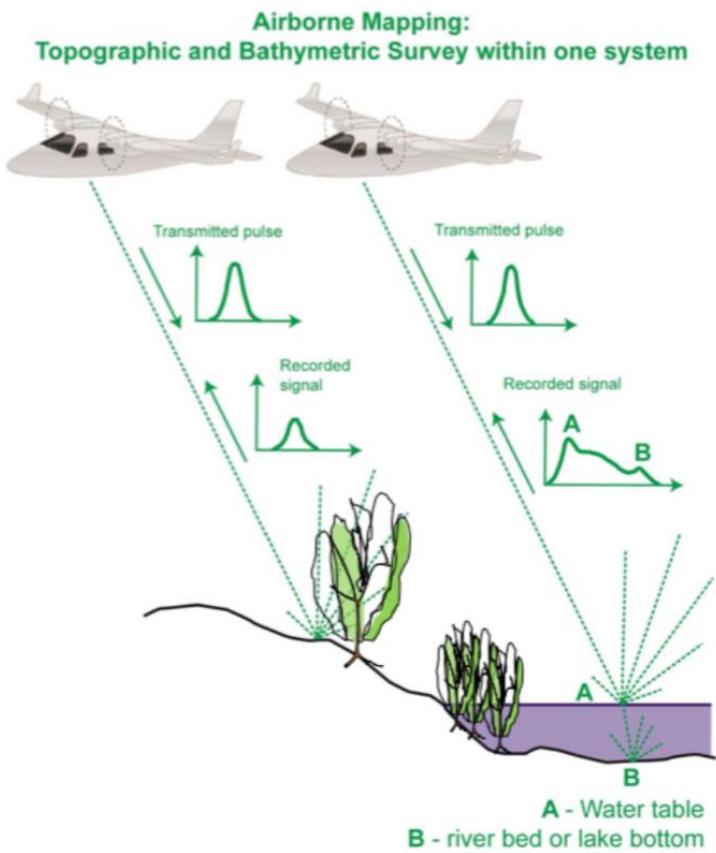
LiDAR



Kvifor LiDAR innan hydrologi?

- Svært presise terrengmodellar
 - Grunnlag for å finne hydrologiske data
 - Basis for detaljerte fordelte hydrologiske modellar
- For å sjå på endring i geometri
 - erosjon/sedimentering
- Grunnlag for modellering av hydraulikk
 - Ulike problemstillingar i vassdrag
 - Detaljert geometri gir bedre modellar
 - Modellering av strømning over terreng - flom

LiDAR



Preprocessing

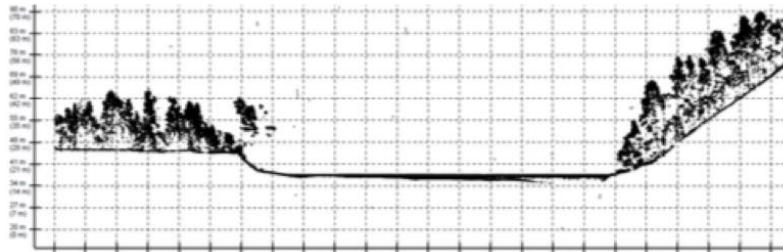
Removal of Flaw Echoes

Classification

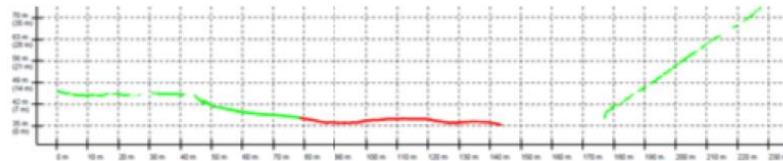
Correction of Refraction

Data Export

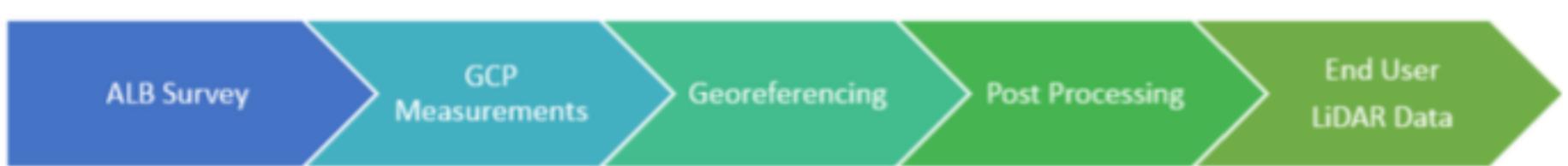
Dataprosesering



(a) Unclassified cross section

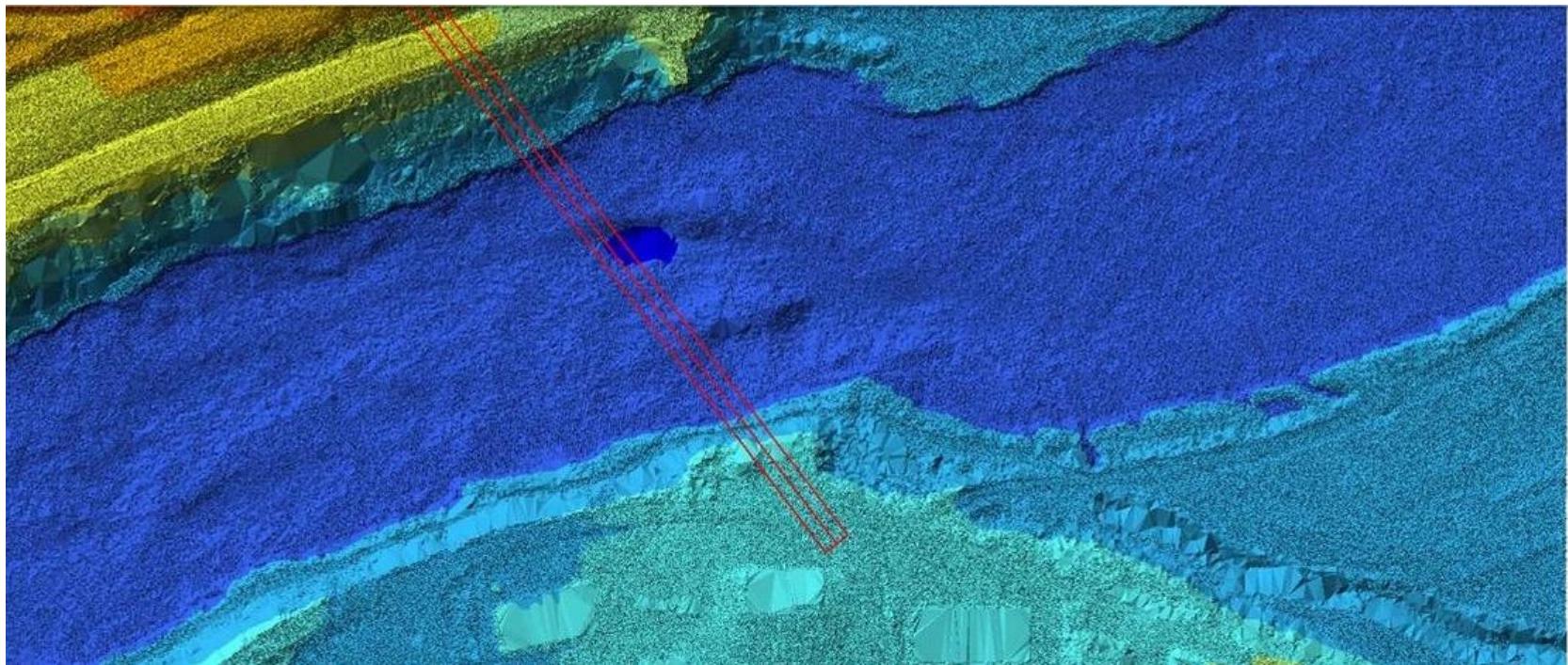


(b) Classified cross sections with river bed (red) and banks (green)

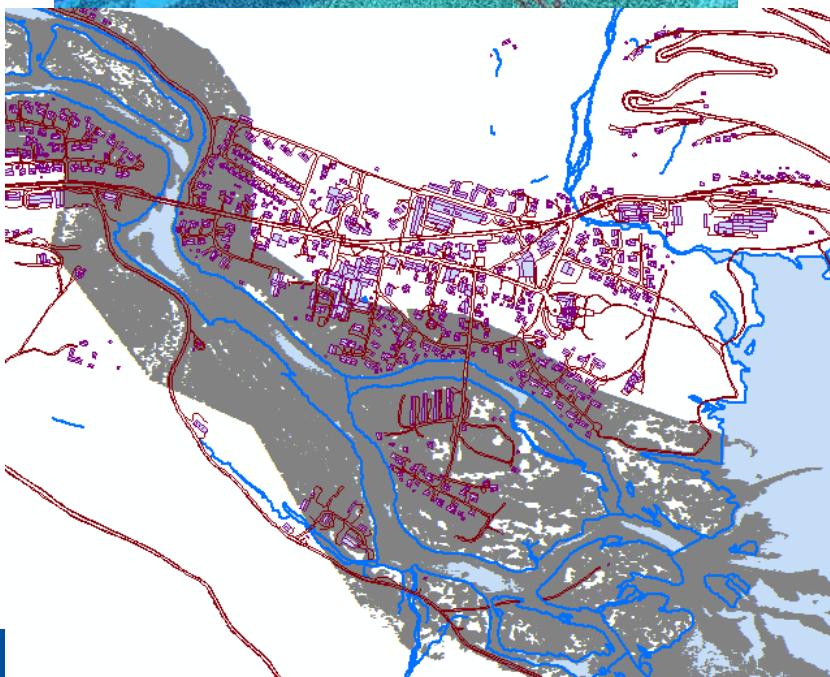
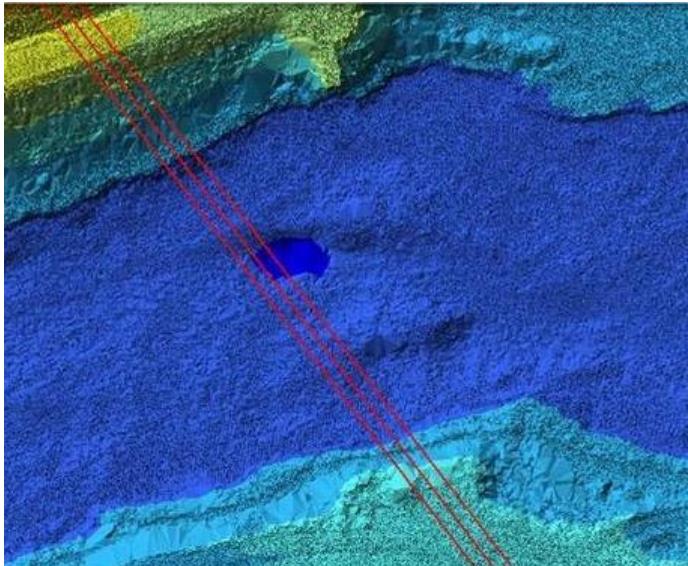


Data

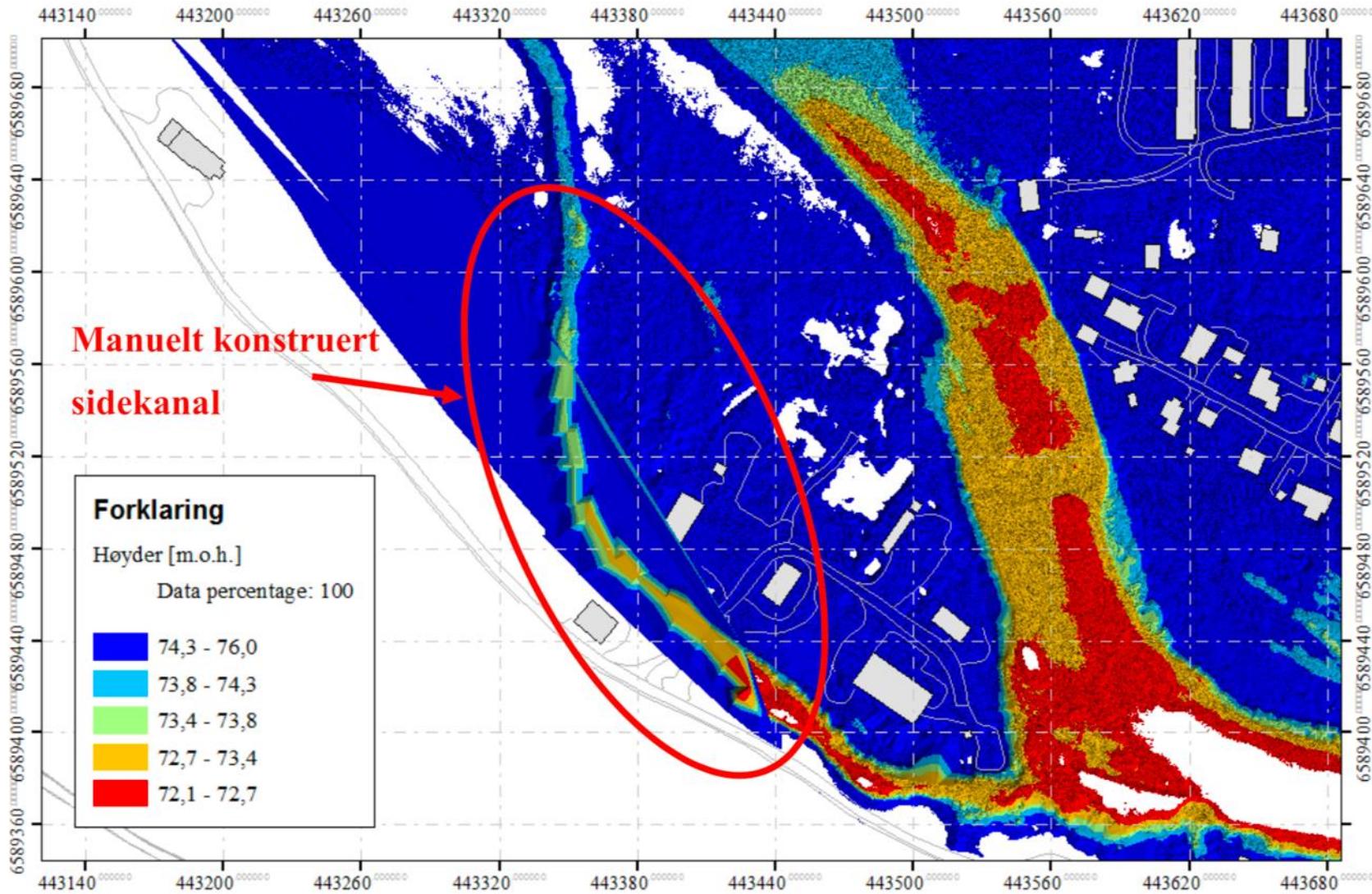
- Punktdata på LAS format – klassifiserte etter type
- Ulike produkt, t.d. 1 x 1 meter terrengmodell, tverrprofil
- LAS gir størst fleksibilitet – lage eigne terrengmodellar med den oppløysinga ein vil ha.



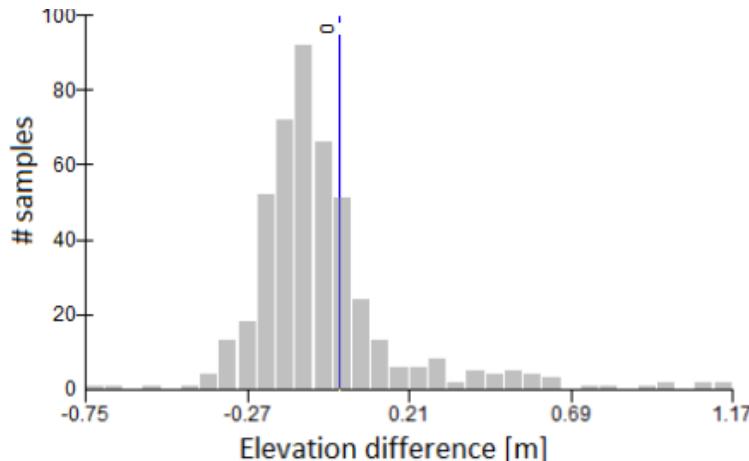
Manglende data ved bruk av grøn laser



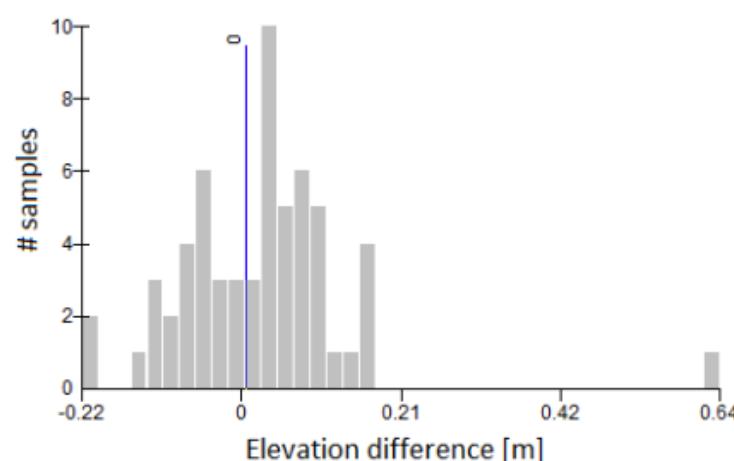
Manglende data



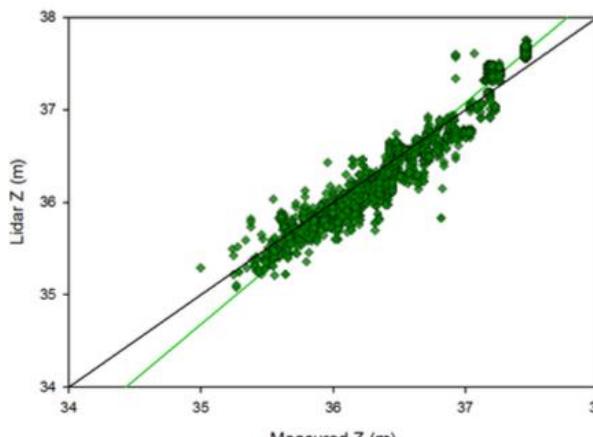
Vurdering av data - Ljungan



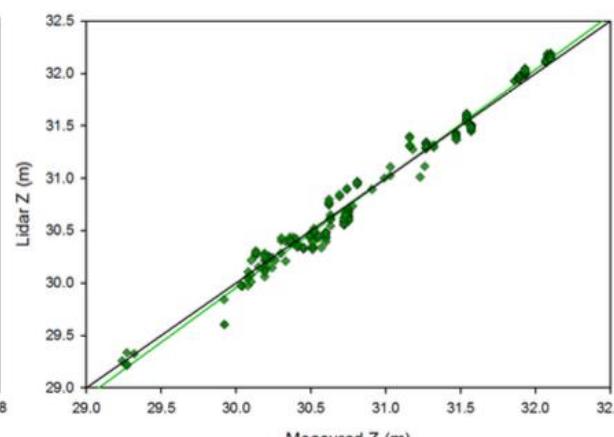
(a) Deep glide



(b) Pool



(a) Deep glide $R^2=0.97$

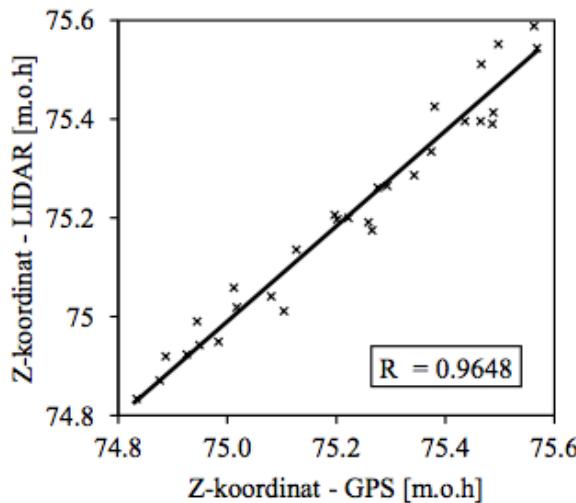


(b) Pool $R^2=0.98$

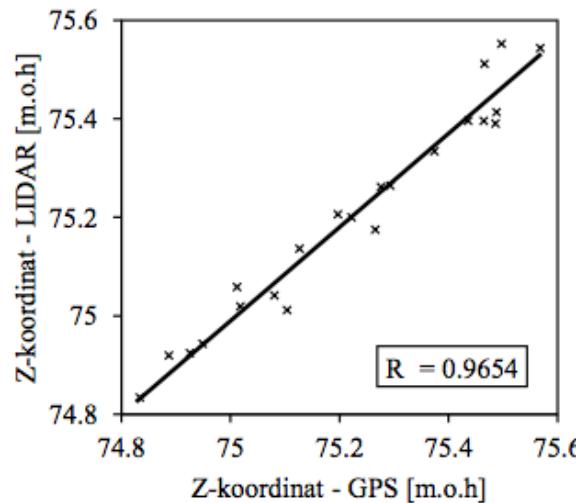
Målt på djupt vann med DPGS og sonar. Basert på nærmeste punkt.
Omrekna til ortometrisk med gjennomsnitsverdi

Vurdering av data - Tokke

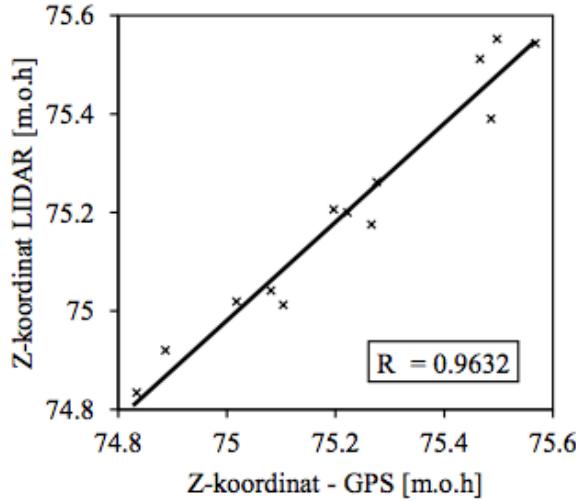
Avstand < 0.5 m



Avstand < 0.1 m

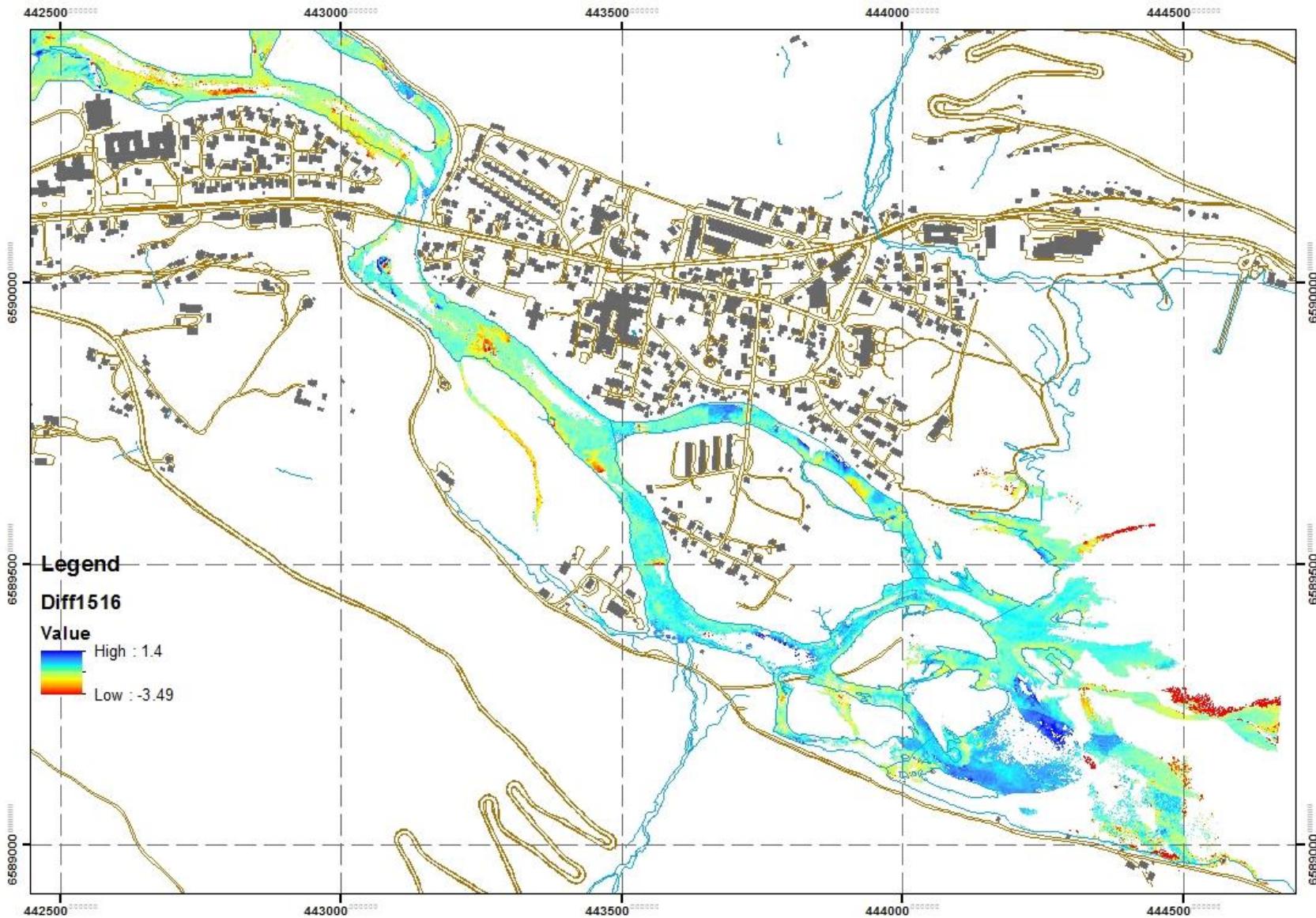


Avstand < 0.05 m

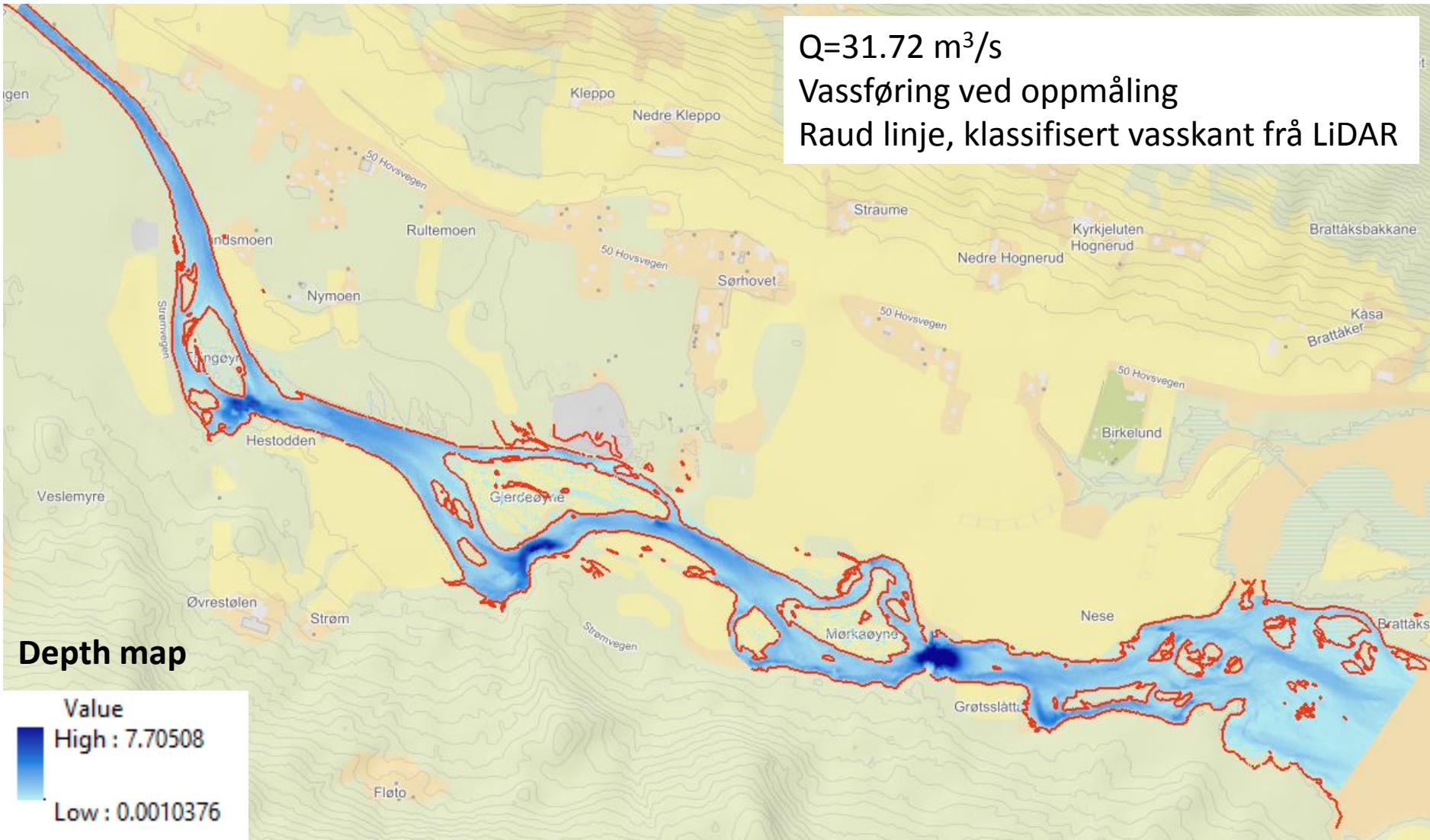


Sted	Avstand [m]	Antall data	Middelfeil [m]	Standardavvik [m]	R^2
Fotballbane ved skolen (GPS)	0.5	29	0.16	0.035	0.85
	0.1	20	0.15	0.035	0.86
	0.05	13	0.14	0.031	0.84
Buøy camping (GPS)	0.5	31	0.017	0.044	0.96
	0.1	23	0.021	0.044	0.97
	0.05	14	0.019	0.049	0.96
Nedstrøms bru (ADCP)	1	1788	-0.021	0.29	0.72
	0.5	1647	-0.0087	0.27	0.75
	0.1	598	0.049	0.23	0.71
Oppstrøms Buøy (ADCP)	0.05	185	0.054	0.23	0.68
	1	221	-0.070	0.16	0.88
	0.5	149	-0.079	0.17	0.80
(ADCP)	0.1	42	-0.028	0.14	0.85
	0.05	11	-0.0071	0.13	0.87

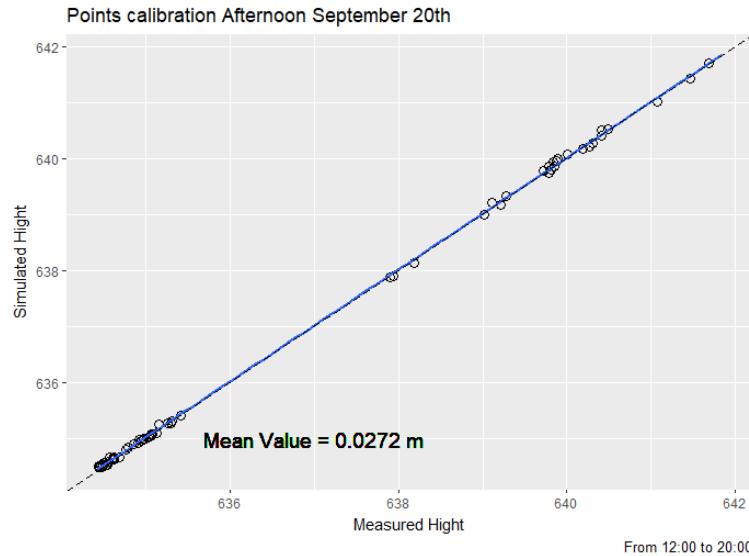
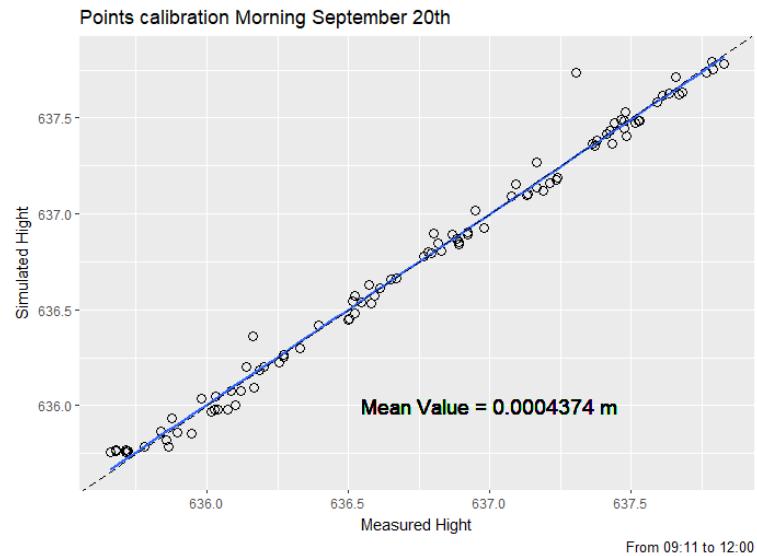
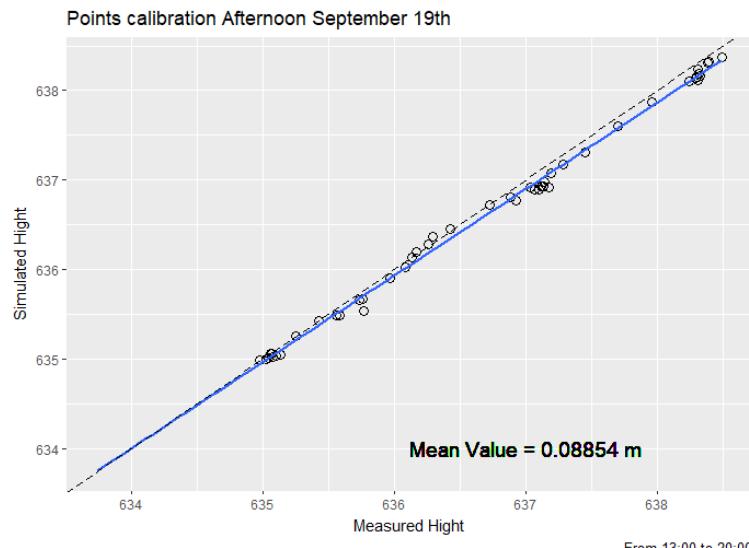
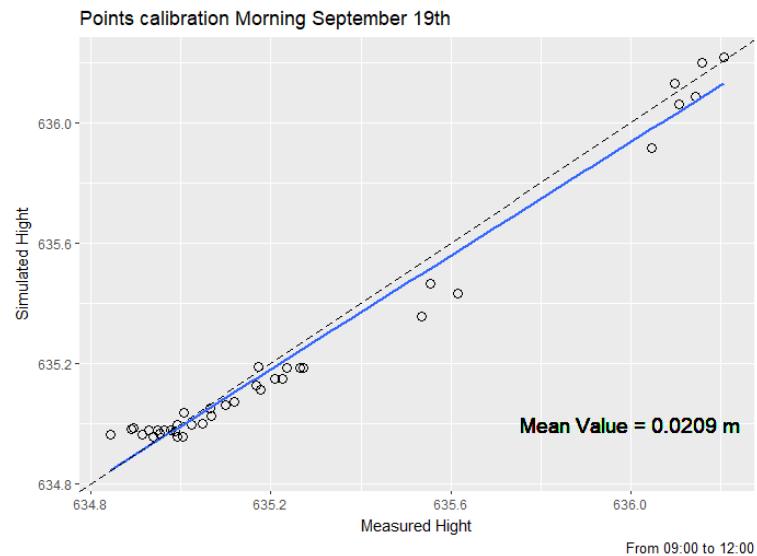
Endring i geometri



Modellering av tørrlegging



Kontroll målt vannlinje



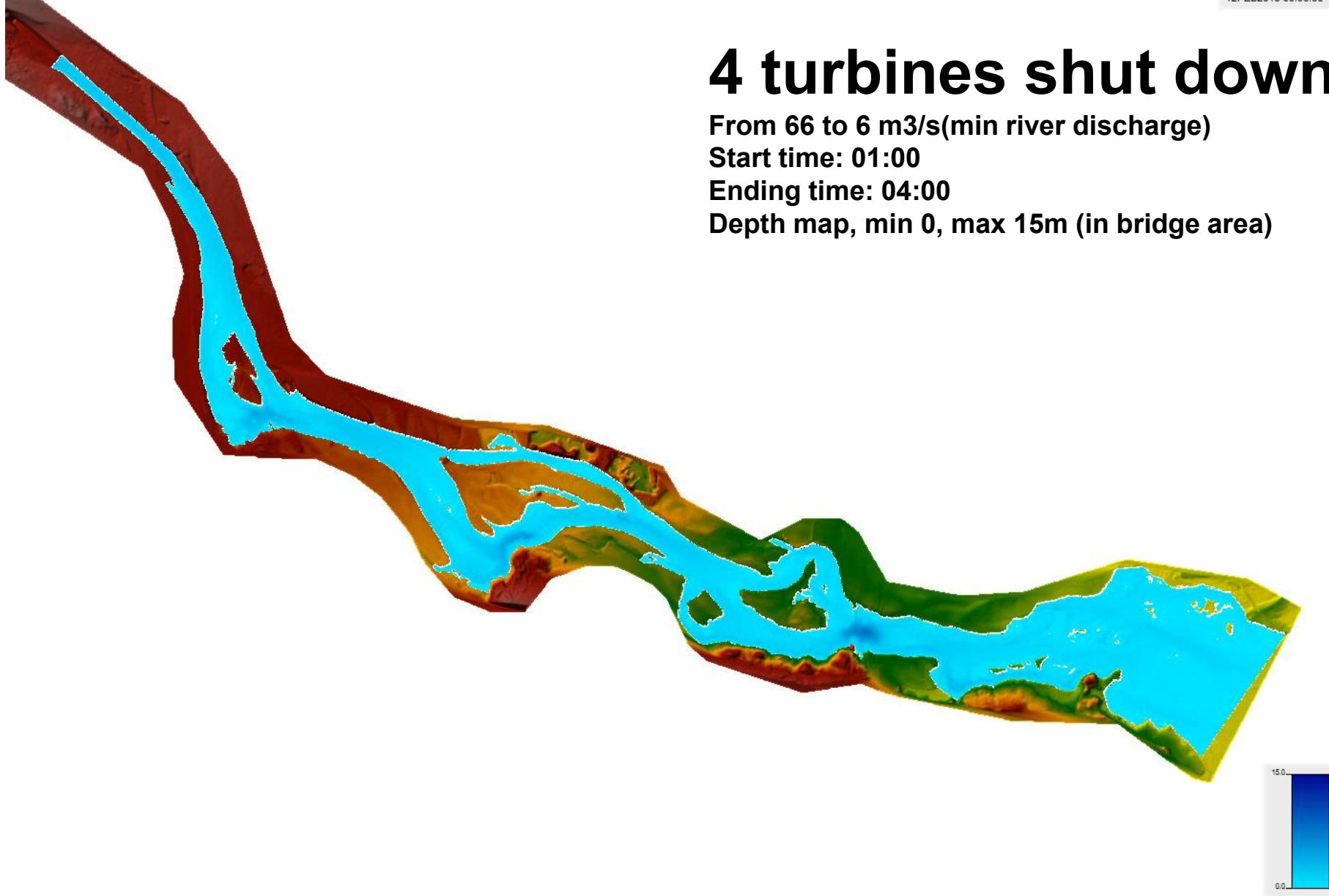
4 turbines shut down

From 66 to 6 m³/s(min river discharge)

Start time: 01:00

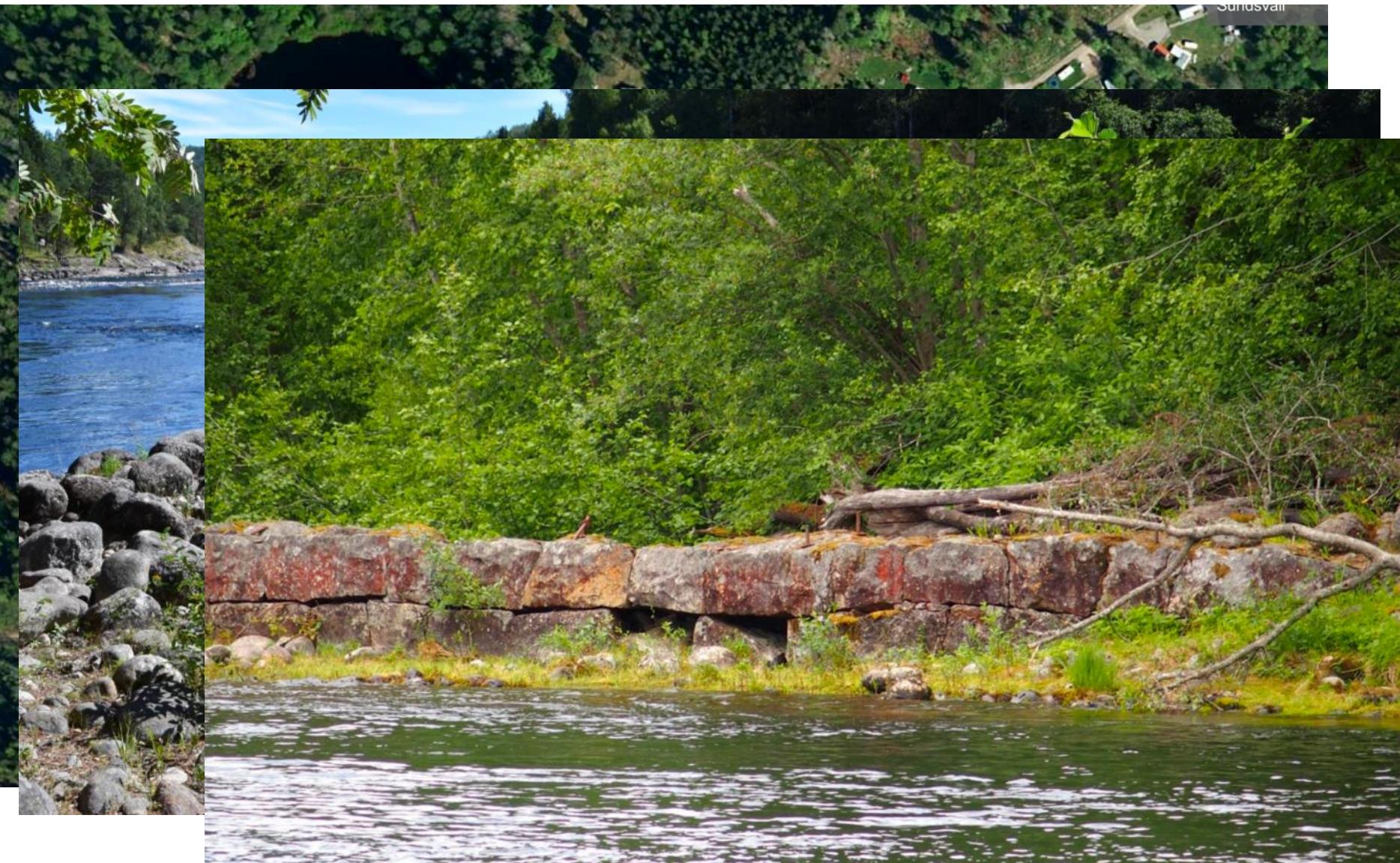
Ending time: 04:00

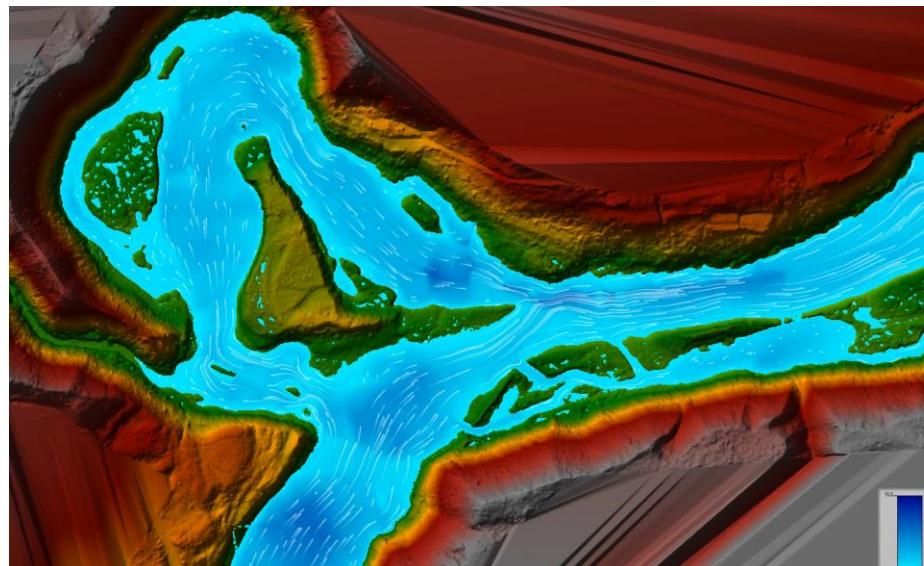
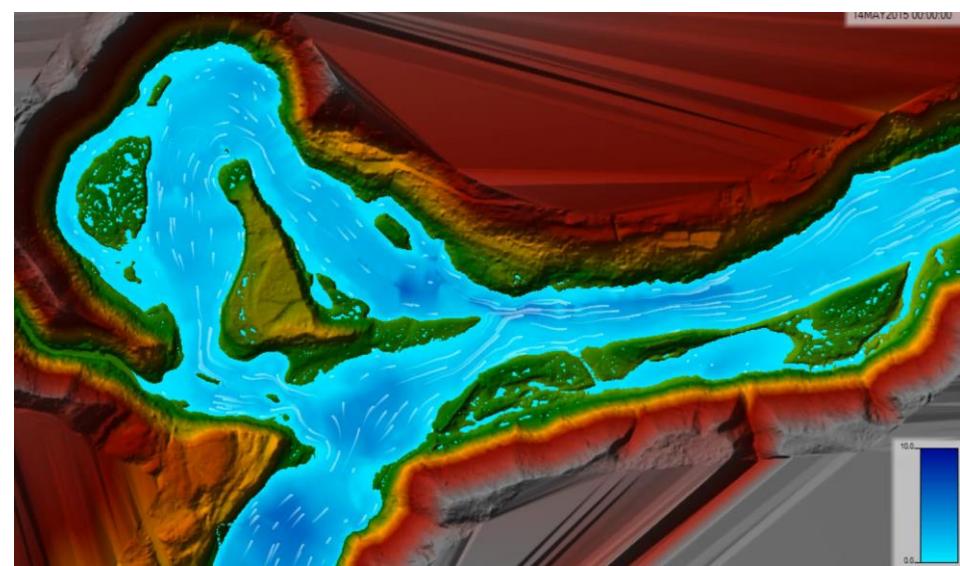
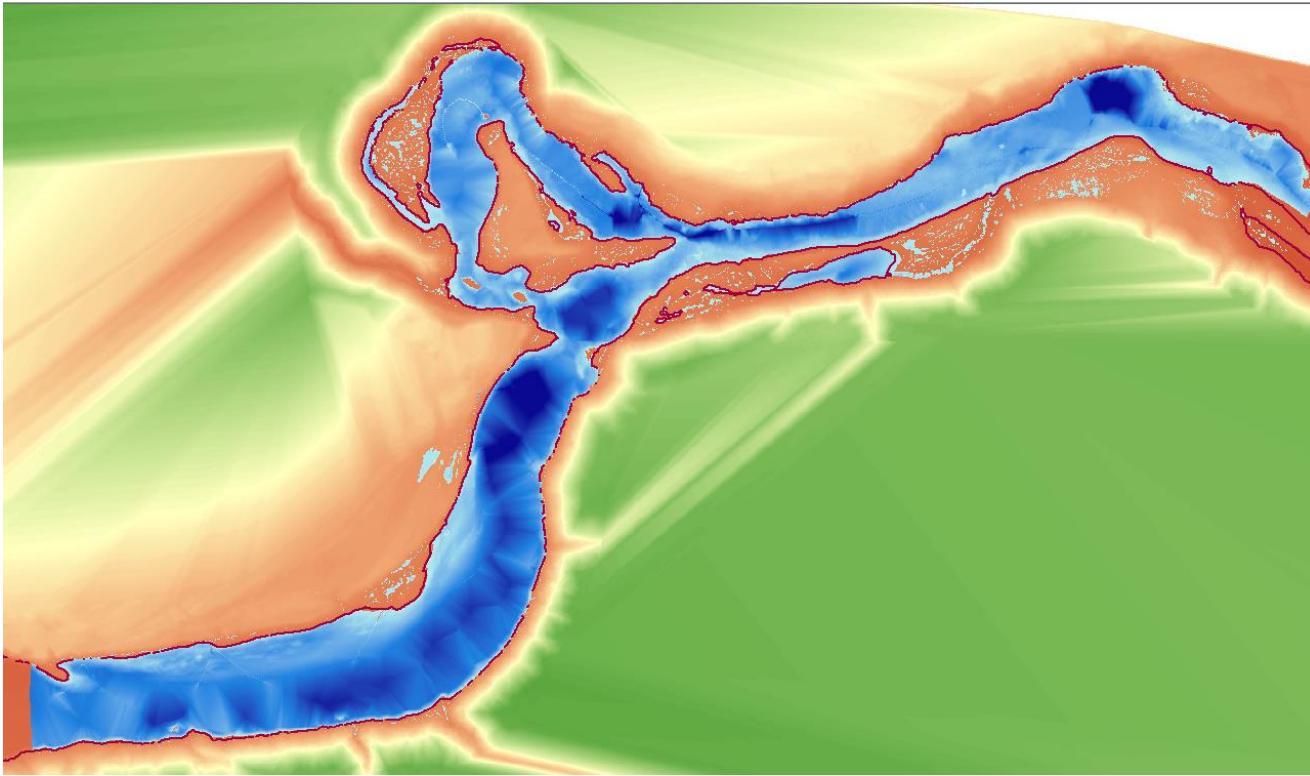
Depth map, min 0, max 15m (in bridge area)



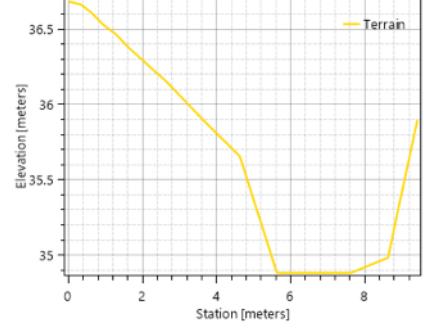
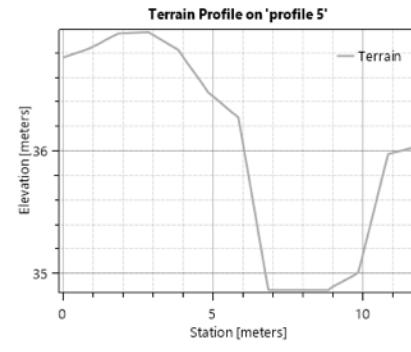
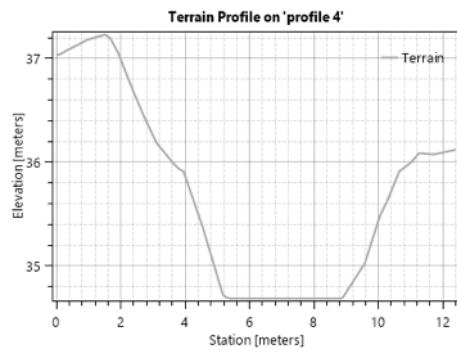
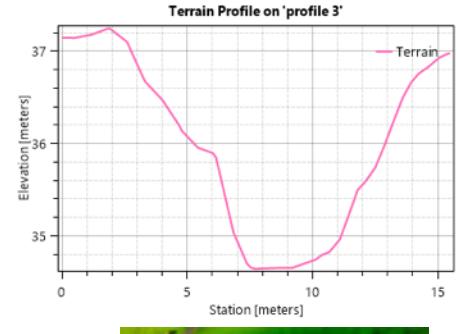
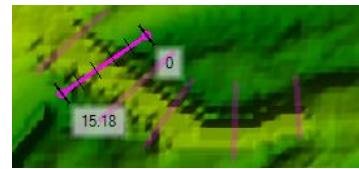
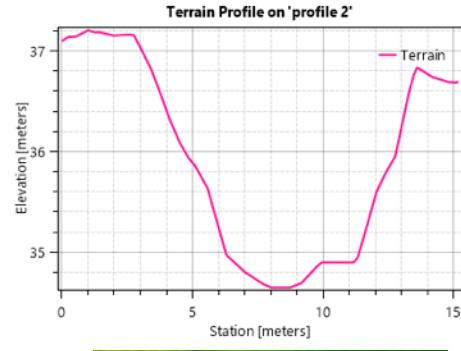
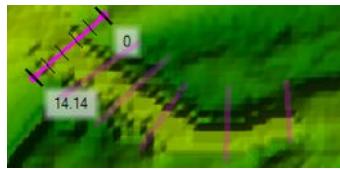
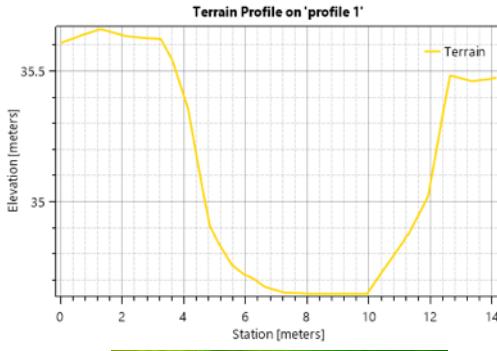
Restaurering av vassdrag

Sundsvall





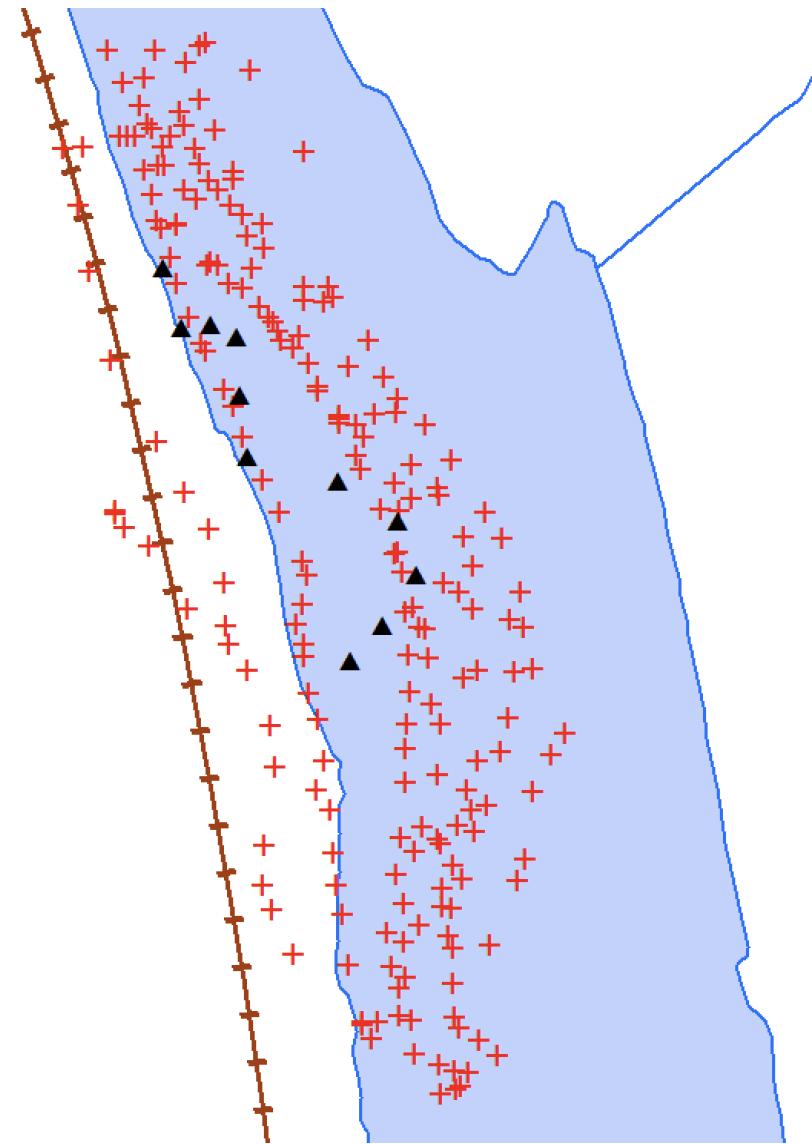
Utforming av ny kanal



Grenforsen – etter endringar

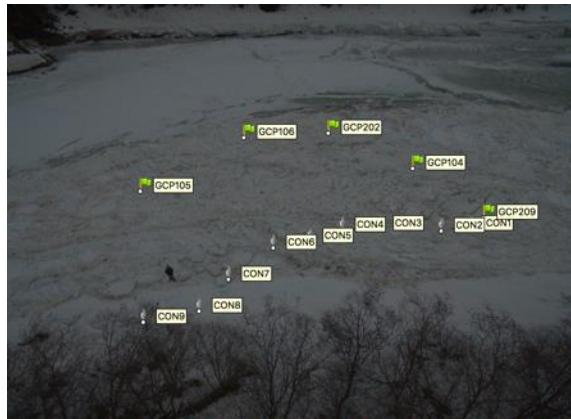


Kopling LiDAR andre geometridata



Structure from motion

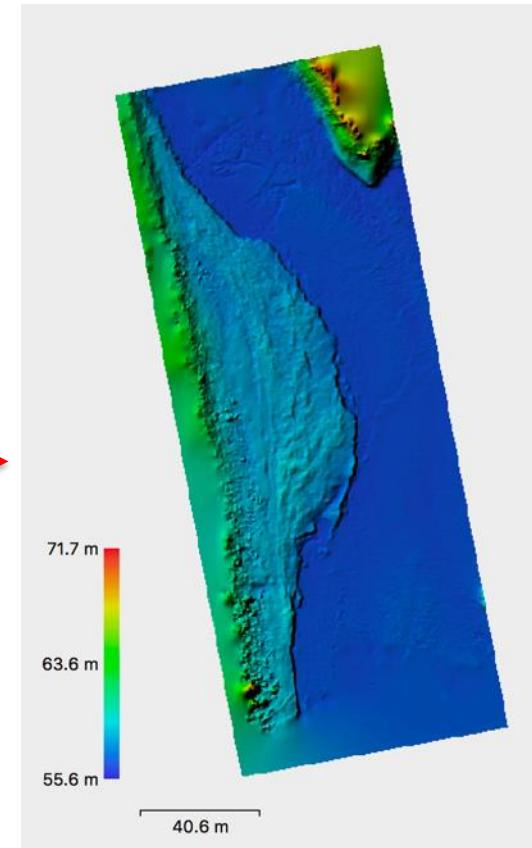
Bilete med kontrollpunkt



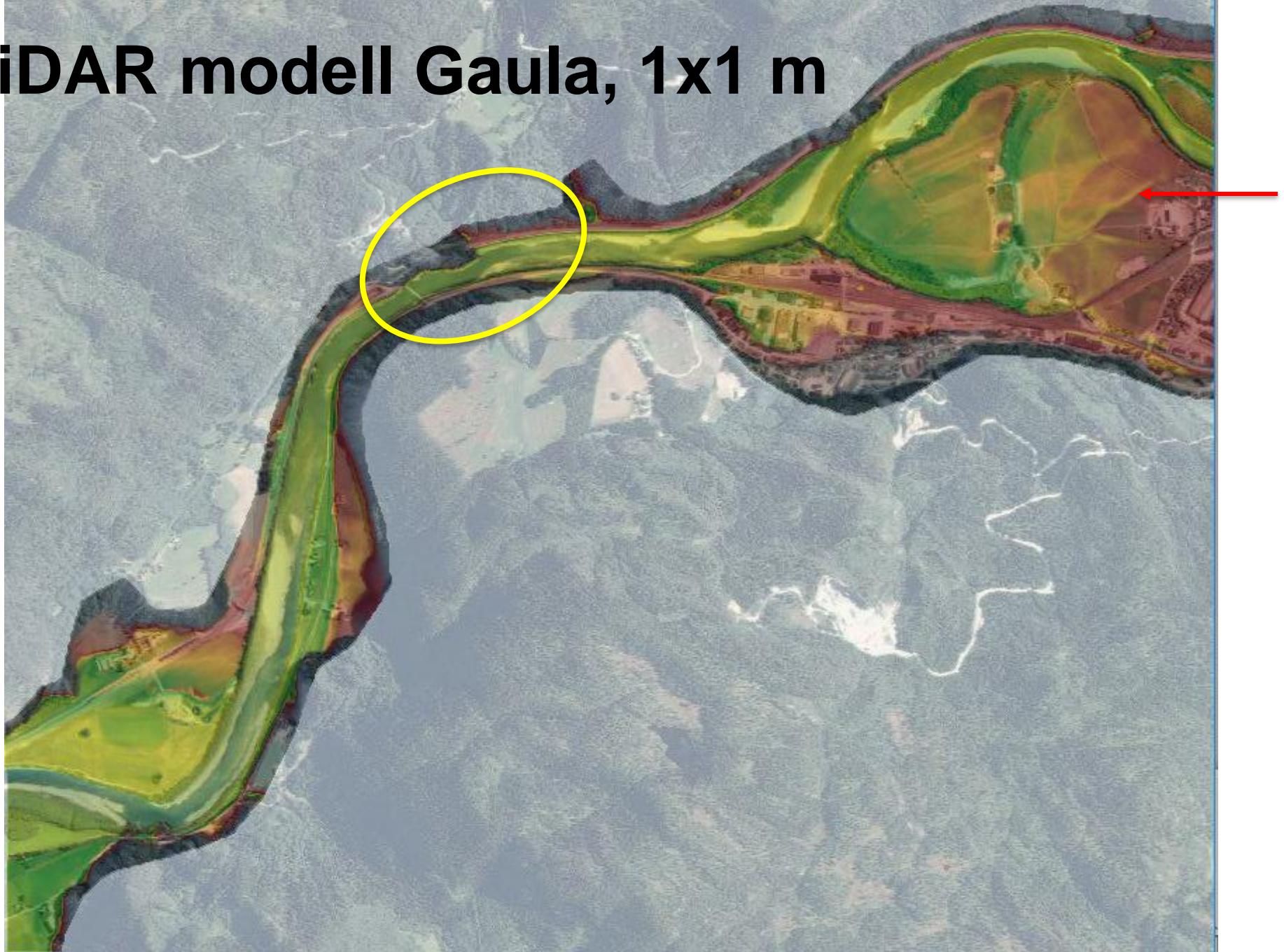
Punktsky



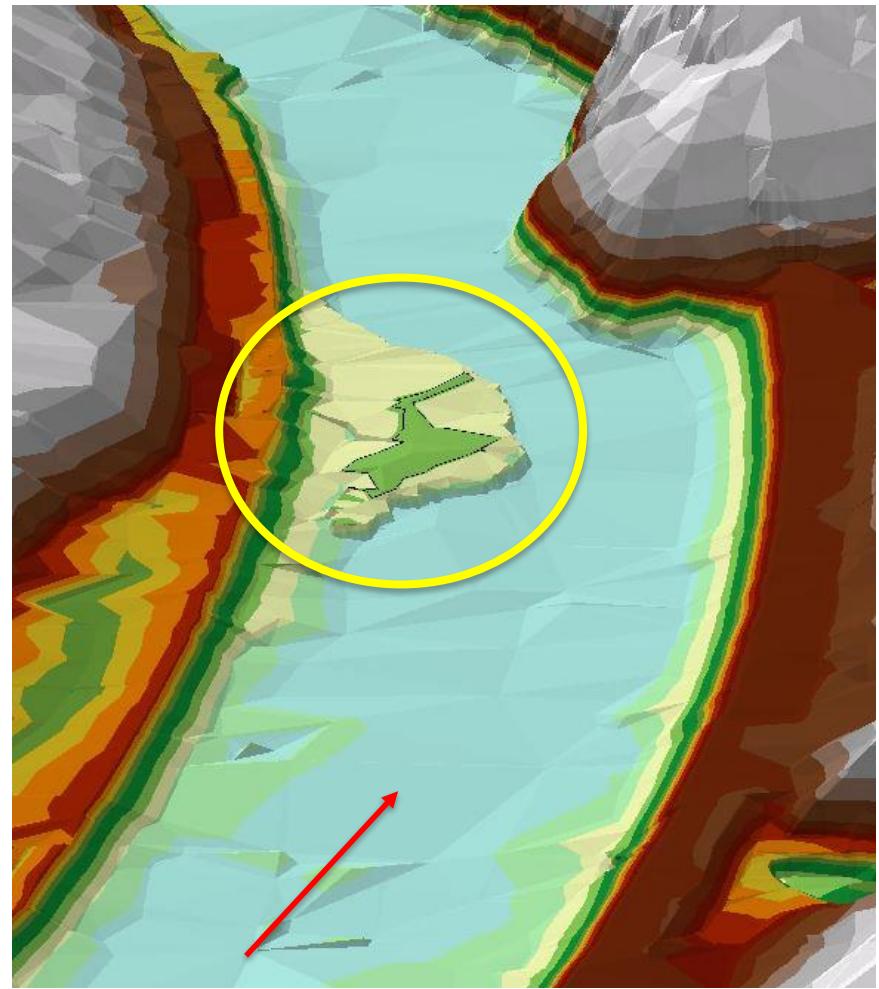
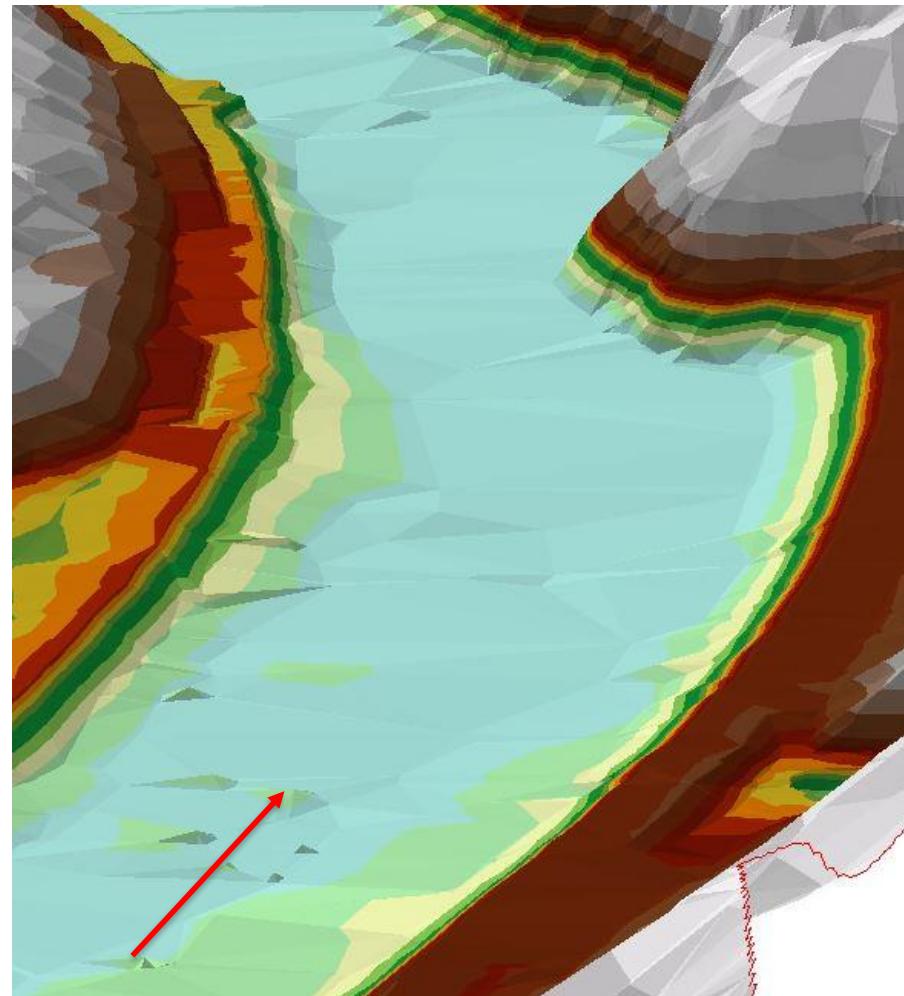
Digital Terreng Modell



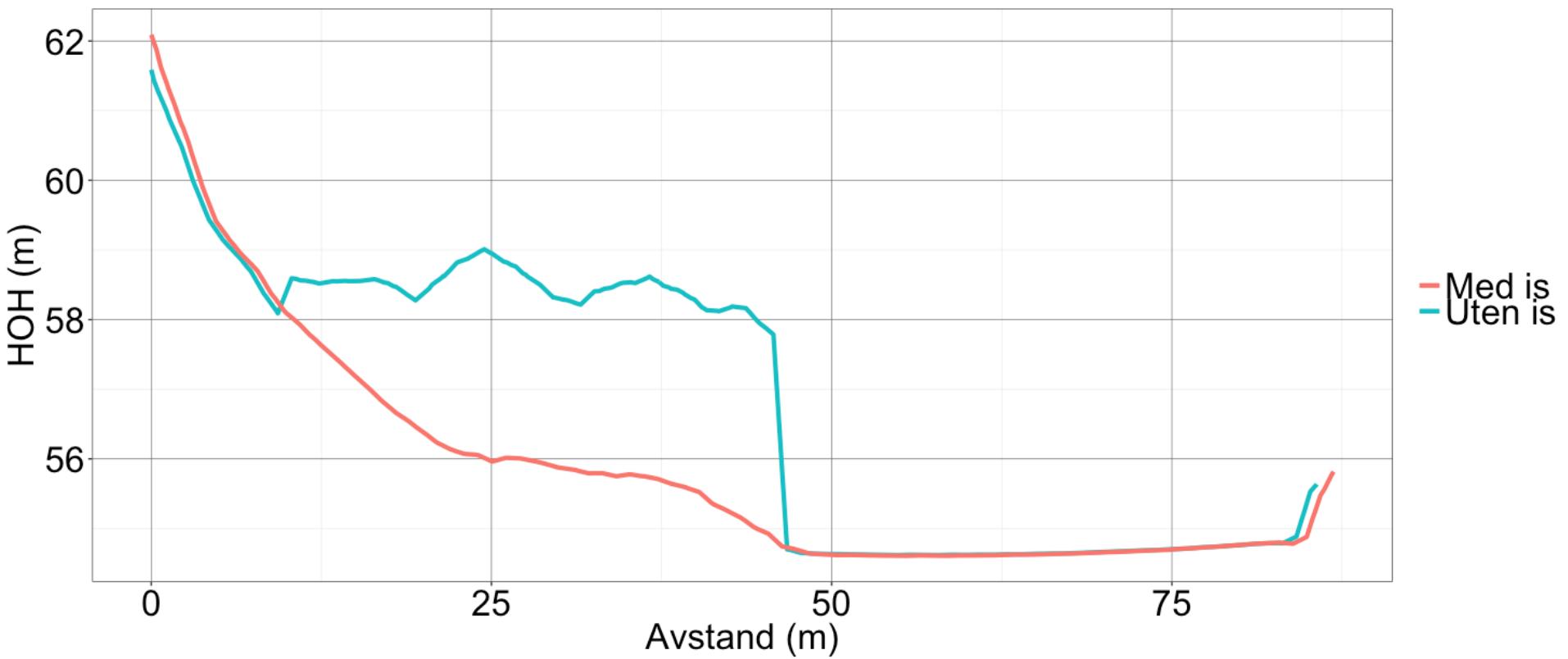
LiDAR modell Gaula, 1x1 m

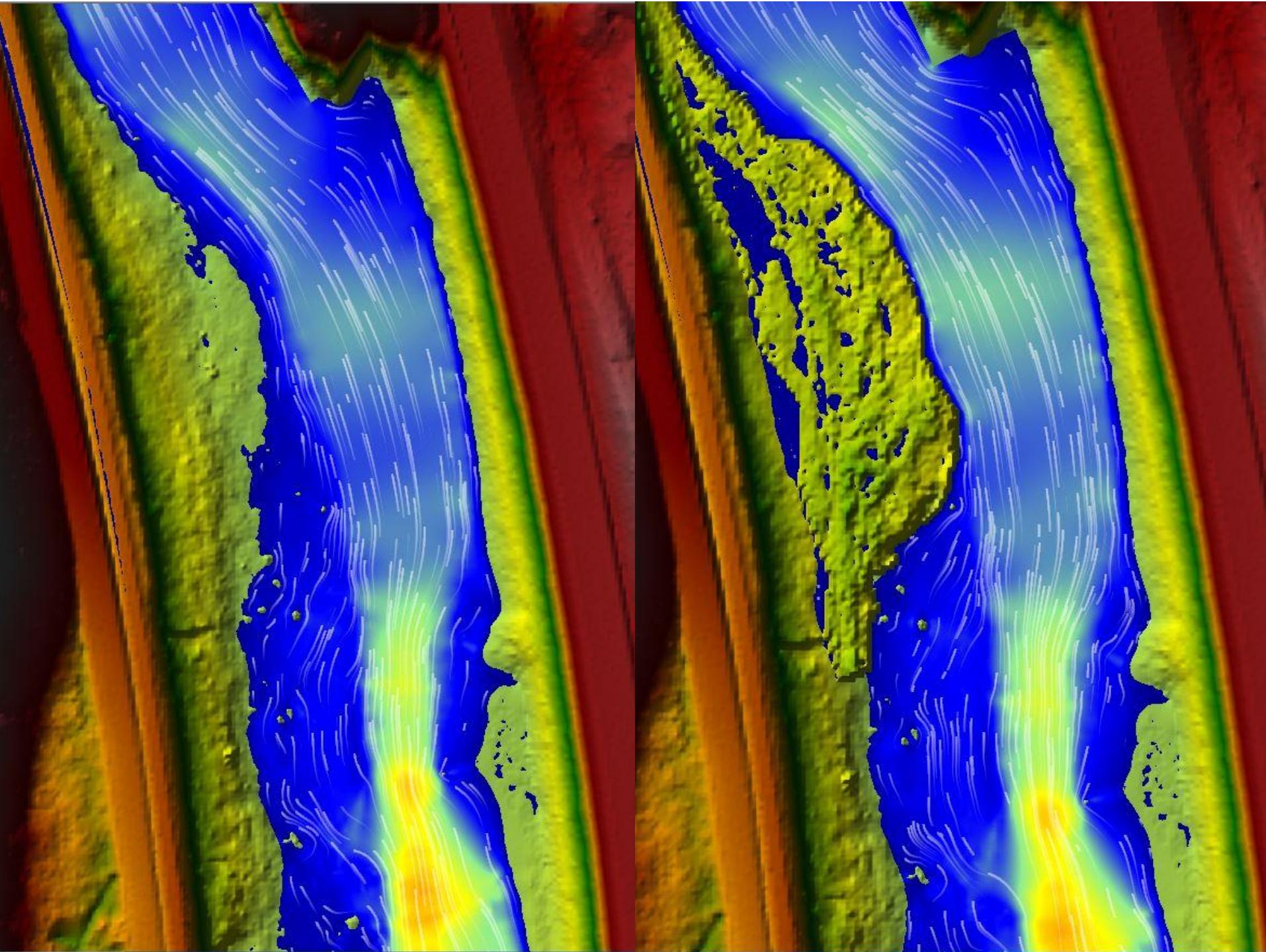


Batymetri med og utan is



Tverrprofil





Oppsummering

- Effektiv måte å skaffe svært detaljerte datasett
- Presisjonen verkar å vere god.
- Grunnlag for analyse av terrenget - t.d. erosjon
- Svært godt grunnlag for modellering innan hydrologi og hydraulikk

Takk til: Ingrid Alne, Ragnhild Hammeren, Ana Adeva Bustos, Carole Rozier, Aurelie Gosset, Iacopo Muscara, Lars Skeie, Konstantina Papanikolaeu og Ana Juarez.

Morten Stickler, Bjørn Otto Dønnum og NVE for data.