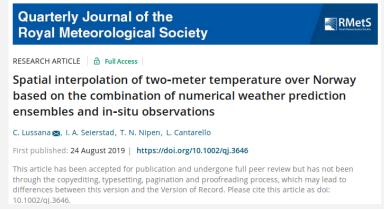


New short-range weather forecast products improved by citizen observations

Cristian Lussana, Thomas Nipen, Ivar Seierstad and Christoffer Elo Norwegian Meteorological Institute, Oslo, Norway

17 September 2019 - 5th Conference on Modelling Hydrology, Climate and Land Surface Processes, Lillehammer, Norway

Ensemble Statistical Interpolation (EnSI) that is an adaptation of Local Ensemble Transform Kalman Filter to spatial analysis



Lussana, C., Seierstad, I. A., Nipen, T. N. and Cantarello, L. (2019), Spatial interpolation of two-meter temperature over Norway based on the combination of numerical weather prediction ensembles and in-situ observations. Q J R Meteorol Soc. Accepted Author Manuscript. doi:10.1002/qj.3646

Also related:

Nipen, T. N., Seierstad, I. A., Lussana, C., Kristiansen, J. and Hov Ø. (2019), Adopting citizen observations in operational weather prediction. Bull. Amer. Meteor. Soc., currently under review

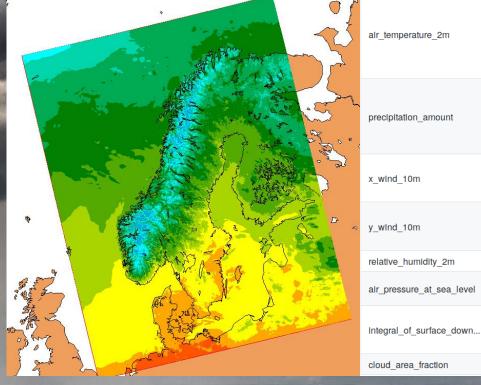


MET Nordic dataset

not only rain...

1 km grid, Scandinavia

data since 2013



NWP post-processing

+ observations for precipitation and temperature



Meteorologisk institutt

Why do we need statistical post-processing for nowcasting of 1km-scale weather?

Can't we simply run the model more often?



Why do we need statistical post-processing for nowcasting of 1km-scale weather?

Can't we simply run the model more often?

we would need to run it very-very often and with a massive amount of new 1km-scale observations



Three different ways to include new "local" observations in a cloud-resolving Local Atmospheric Model

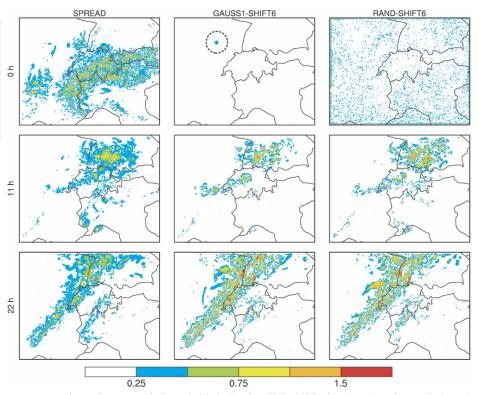


Fig. 2. Comparison of different perturbation methodologies, i.e., (left) shifting initialization, (center) Gaussian perturbation, and (right) random numbers valid after 0, 11, and 22 h of integration at 1-km height (K). The panels show temperature spread \mathcal{S} (for the shifting initialization technique) and temperature difference \mathcal{D} (for the other techniques). The dashed line indicates the footprint of the initial Gaussian perturbation associated with GAUSS1 in the lowermost model layer. The maps cover an area of approximately $882 \text{ km} \times 662 \text{ km}$ ($401 \times 301 \text{ grid points}$).



Three different ways to include new "local" observations in a cloud-resolving Local Atmospheric Model

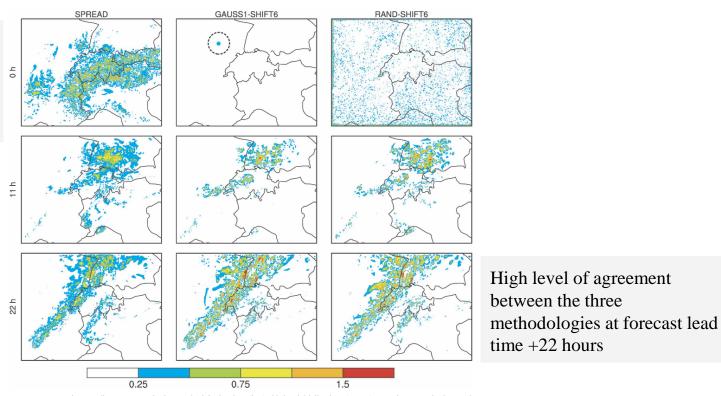


Fig. 2. Comparison of different perturbation methodologies, i.e., (left) shifting initialization, (center) Gaussian perturbation, and (right) random numbers valid after 0, 11, and 22 h of integration at 1-km height (K). The panels show temperature spread S (for the shifting initialization technique) and temperature difference D (for the other techniques). The dashed line indicates the footprint of the initial Gaussian perturbation associated with GAUSS1 in the lowermost model layer. The maps cover an area of approximately $882 \text{ km} \times 662 \text{ km}$ ($401 \times 301 \text{ grid points}$).



Three different ways to include new "local" observations in a cloud-resolving Local Atmospheric Model

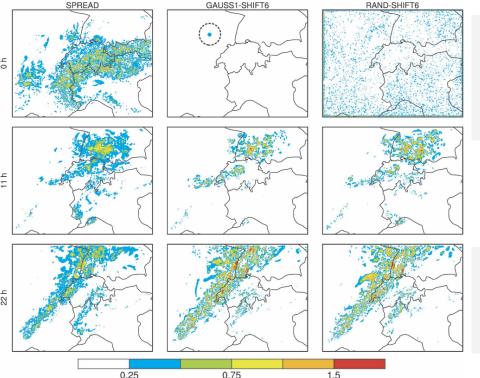


Fig. 2. Comparison of different perturbation methodologies, i.e., (left) shifting initialization, (center) Gaussian perturbation, and (right) random numbers valid after 0, 11, and 22 h of integration at 1-km height (K). The panels show temperature spread S (for the shifting initialization technique) and temperature difference D (for the other techniques). The dashed line indicates the footprint of the initial Gaussian perturbation associated with GAUSSI in the lowermost model layer. The maps cover an area of approximately $882 \text{ km} \times 662 \text{ km} (401 \times 301 \text{ grid points}).$

Lost memory of the local information

The model evolution is forced by something else (boundary conditions ...)



High level of agreement between the three methodologies at forecast lead time +22 hours



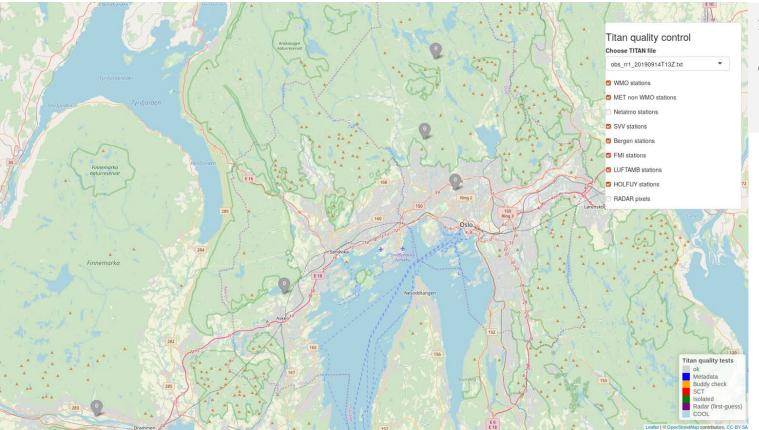
statistical post-processing for nowcasting



remedy for short term memory loss in NWP



Why use citizen observations?



2019-09-14 13:00 UTC

Oslo

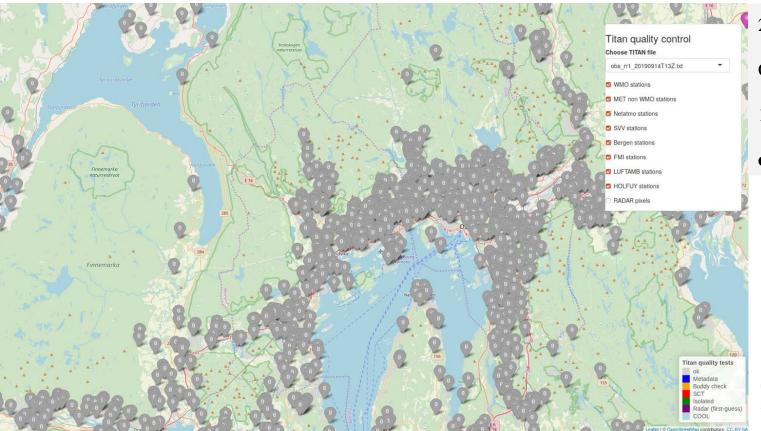
1-hour precipitation tot

most likely, no rain over most part of the region





to gain confidence in our predictions



2019-09-14 13:00 UTC

Oslo

1-hour precipitation tot

citizen observations

no rain over Oslo, Drammen and the coast of the Oslo fjord. Most likely, no rain in the forests



...even better if we have multiple sources



2019-09-14 13:00 UTC

Oslo

1-hour precipitation tot citizen observations

radar estimates

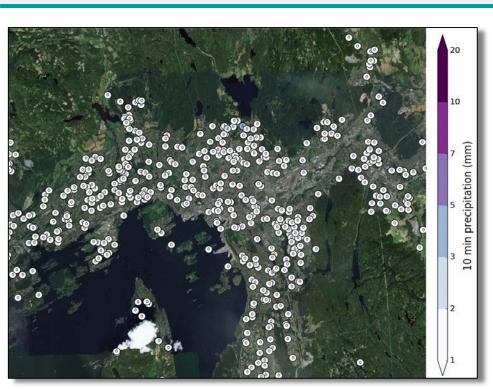
no rain.





...citizen observations turn out to be useful even when it is raining...

Extreme local precipitation in Oslo

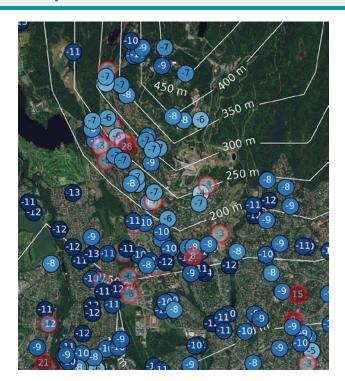


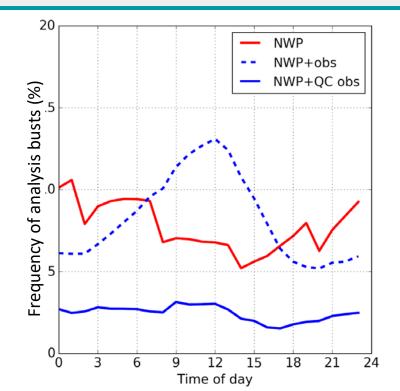


Quality control is essential to get value!

Network should be treated as a whole, not as individual stations

Only 20% are removed in our conservative QC

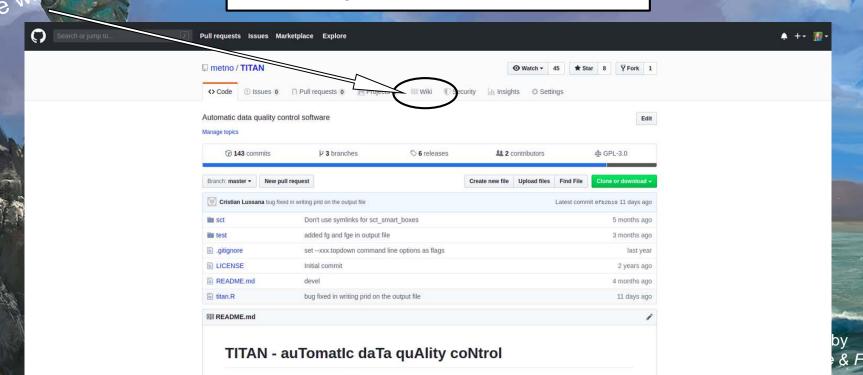


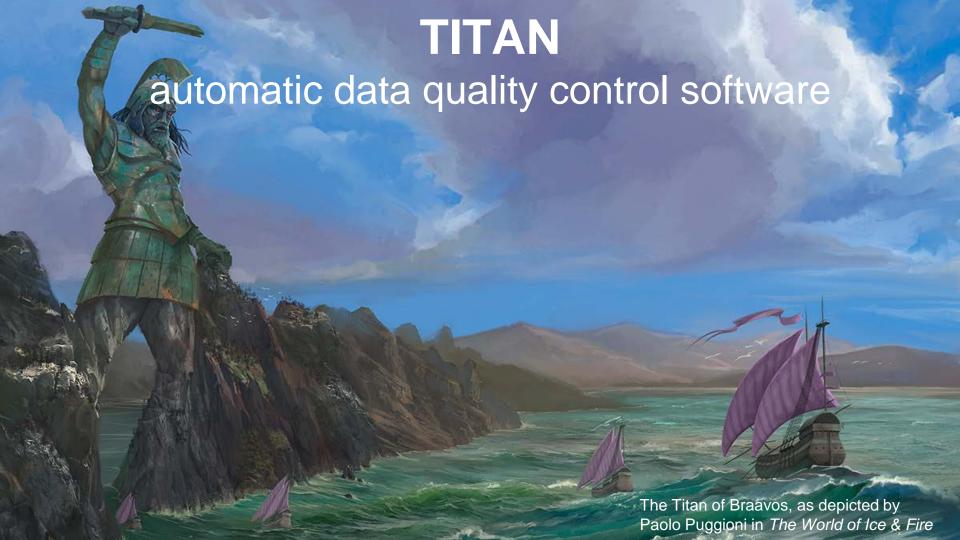


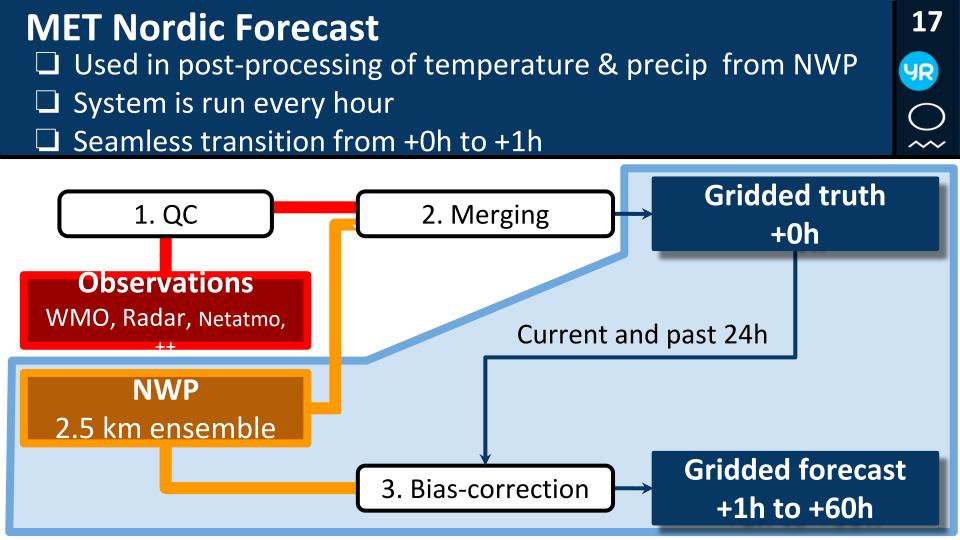
TITAN

automatic data quality control software

https://github.com/metno/TITAN

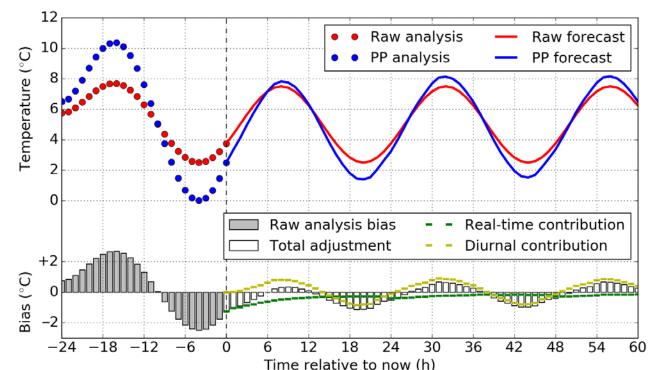






3. Bias-correction

- ☐ Gridpoint by gridpoint correction
- Seamless transition from gridded truth to gridded forecast
- ☐ Diurnally varying bias based on last 24 hours

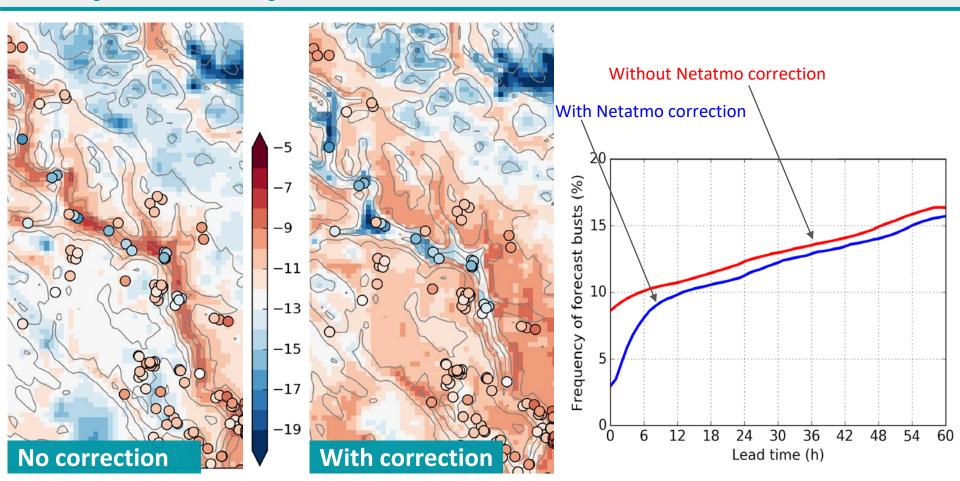


18





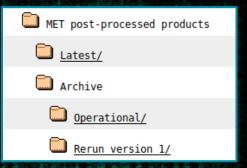
Impact on operational forecasts



MET Nordic Analysis and Forecasts

Production strategy:

- Hourly updates
- Reruns when significant improvements on
 - observational data
 - data quality control methods
 - statistical post-processing methods
- OpenData access on thredds.met.no
- Wiki https://github.com/metno/NWPdocs/wiki/Post-processed-products







Norwegian Meteorological Institute

Cristian Lussana, MET Norway, Oslo

Telephone: +47 22 96 30 00

E-mail: cristian.lussana@met.no

Website: met.no yr,no



Supplementary Material



Norwegian Meteorological Institute